

PARAMETERIZED COMPLEXITY OF MINCSP OVER THE POINT ALGEBRA

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Constraint Satisfaction Problem (CSP) over Point Algebra

Point Algebra is the set of relations $\{<, >, \leq, \geq, =, \neq\}$ over \mathbb{Q} .

Let us fix a *constraint language* $\Gamma \subseteq \{<, >, \leq, \geq, =, \neq\}$.

CSP(Γ) input is (V, \mathcal{C}) , where

- V is a set of variables,
- \mathcal{C} is a set of constraints of the form $u \odot v$ with $u, v \in V$ and $\odot \in \Gamma$.

Q: is there $\alpha : V \rightarrow \mathbb{Q}$ that *satisfies* all constraints in \mathcal{C} ?

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Ex:

$$v_1 \leq v_2, \quad v_1 \neq v_2, \quad v_2 > v_3$$

is satisfiable, e.g. $\alpha(v_1) = 1, \alpha(v_2) = 2, \alpha(v_3) = 0$.

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$$v_1 < v_2, \quad v_2 = v_3, \quad v_1 > v_3$$

is not satisfiable.

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CSP(Γ) is solvable in polynomial time for all $\Gamma \subseteq \mathcal{A}$.

Minimum-Cost CSP (MinCSP) over Point Algebra

MINCSP(Γ) input is (V, \mathcal{C}, k) , where

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- k is an integer.

Q: is there $\alpha : V \rightarrow \mathbb{Q}$ that *breaks* at most k constraints in \mathcal{C} ?

Unless MINCSP(Γ) is trivial, it is NP-hard and UGC-hard to $O(1)$ -apx.

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We study parameterized complexity:

FPT	vs	W[1]-hard
$f(k) \cdot n^{O(1)}$	vs	$n^{g(k)}$

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Theorem

Let $\Gamma \subseteq \{<, >, \leq, \geq, =, \neq\}$.

- If $\{\leq, \neq\} \subseteq \Gamma$, then MINCSP(Γ) is $W[1]$ -hard.
- If $\{\geq, \neq\} \subseteq \Gamma$, then MINCSP(Γ) is $W[1]$ -hard.
- Otherwise, MINCSP(Γ) is FPT.

Motivation

For different $\Gamma \subseteq \{<, >, \leq, \geq, =, \neq\}$, $\text{MINCSP}(\Gamma)$ captures Multicut, Directed (Subset) Feedback Arc Set and Directed Symmetric Multicut.

- $\Gamma = \{<\}$: *Directed Feedback Arc Set* is FPT (Chen Liu Lu O'Sullivan Razgon @STOC'08 \rightarrow JACM'08)

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We show that Directed Symmetric Multicut is $W[1]$ -hard, and every $\text{MINCSP}(\Gamma)$ that avoids it is FPT.

MinCSP and Graph Problems

Directed Feedback Arc Set and $\text{MinCSP}(<)$

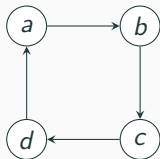
An instance of $\text{CSP}(<)$ is satisfiable iff the digraph is acyclic.

$$a < b$$

$$b < c$$

$$c < d$$

$$d < a$$

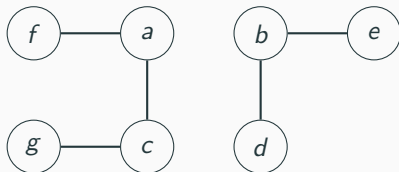


$\text{MinCSP}(<)$ is Directed Feedback Arc Set: given a digraph G and $k \in \mathbb{N}$, delete at most k arcs from G to make it acyclic.

Edge Multicut and MinCSP(=, \neq)

An instance of CSP(=, \neq) is satisfiable iff there is no =-path between disequal variables.

$$\begin{array}{ll} a = c & \\ a = f & a \neq b \\ b = d & c \neq d \\ b = e & e \neq f \\ c = g & f \neq g \end{array}$$



MINCSP(=, \neq) is Edge Multicut¹: given a graph G , a set $\mathcal{T} \subseteq \binom{V(G)}{2}$ and $k \in \mathbb{N}$, delete k edges from G so that no pair in \mathcal{T} is connected.

¹Simple trick allows assuming wlog that \neq -constraints are undeletable.

Directed Symmetric Multicut and $\text{MinCSP}(\leq, \neq)$

An instance of $\text{CSP}(\leq, \neq)$ is satisfiable iff there is no \leq -cycle with two disequal variables.

$$a \leq b$$

$$b \leq c$$

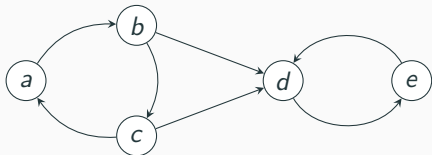
$$c \leq a \quad a \neq d$$

$$b \leq d \quad b \neq e$$

$$c \leq d \quad b \neq c$$

$$d \leq e$$

$$e \leq d$$



$\text{MinCSP}(\leq, \neq)$ is Directed Symmetric Multicut²: given a digraph G , a set $\mathcal{T} \subseteq \binom{V(G)}{2}$ and $k \in \mathbb{N}$, delete k arcs from G so that no pair in \mathcal{T} is strongly connected.

²Simple trick allows assuming wlog that \neq -constraints are undeletable.

Classification

Classification: Case Analysis

$\Gamma \subseteq \{<, >, \leq, \geq, =, \neq\}$, so 2^6 cases.

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Lemma 1: If $\leq \in \Gamma$, then $\text{MINCSP}(\Gamma \cup \{=\}) \leq_{FPT} \text{MINCSP}(\Gamma)$.

Proof: Replace $u = v$ with $u \leq v$ and $v \leq u$. Opt deletes at most one.

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Lemma 2: If $\leq, \neq \in \Gamma$, then $\text{MINCSP}(\Gamma \cup \{<\}) \leq_{FPT} \text{MINCSP}(\Gamma)$.

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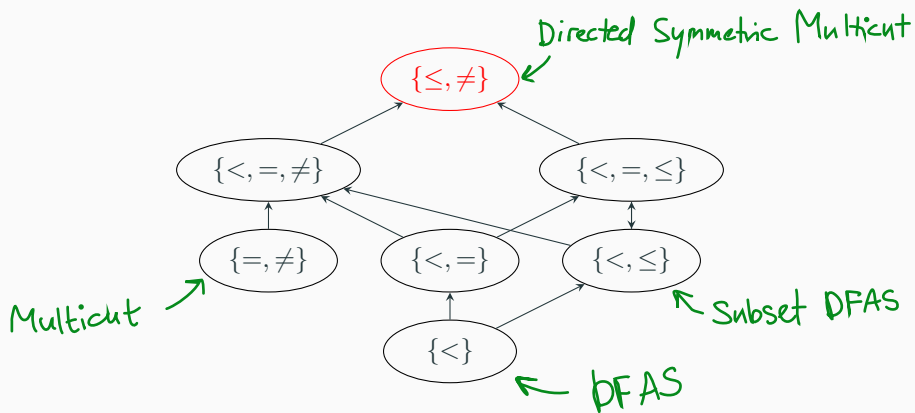
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Lemmas 1 & 2 $\implies \text{MINCSP}(<, \leq, =, \neq) \leq_{FPT} \text{MINCSP}(\leq, \neq)$.

Classification: Map



$\text{MINCSP}(\leq, \neq)$ is $W[1]$ -hard.

$\text{MINCSP}(\lt;, =, \leq) \leq_{\text{FPT}} \text{MINCSP}(\lt;, \leq)$, which is FPT [CCHM].

$\text{MINCSP}(\lt;, =, \neq)$ solved by reduction into BUNDLED ALMOST 2-SAT.

Algorithm

Almost 2-Sat

ALMOST 2-SAT input is (V, \mathcal{C}, k) , where

- V is a set of variables,
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- k is an integer.

Q: is there $\alpha : V \rightarrow \{0, 1\}$ that *breaks* at most k constraints in \mathcal{C} ?

ALMOST 2-SAT is FPT [Razgon O'Sullivan ICALP'08→JCSS'09]

Bundled Almost 2-Sat

In BUNDLED ALMOST 2-SAT, constraints are 2-SAT formulas, e.g.:

1. $(a \vee b) \wedge (\bar{c} \vee \bar{d})$
2. $(a \rightarrow b) \wedge (b \rightarrow c) \wedge (c \rightarrow d)$
3. $(a \vee b) \wedge (\bar{a} \vee \bar{b})$

Theorem (Kim Kratsch Pilipczuk Wahlström SODA'23)

BUNDLED ALMOST 2-SAT is FPT^3 if all formulas are $2K_2$ -free.

³w.r.t. $k + \max$ formula length

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1. $(a \vee b) \wedge (\bar{c} \vee \bar{d})$
Edges $\{ab, cd\}$: not $2K_2$ -free
2. $(a \rightarrow b) \wedge (b \rightarrow c) \wedge (c \rightarrow d)$
Edges $\{ab, bc, cd\}$: $2K_2$ -free
3. $(a \vee b) \wedge (\bar{a} \vee \bar{b})$
Edges $\{ab\}$: $2K_2$ -free

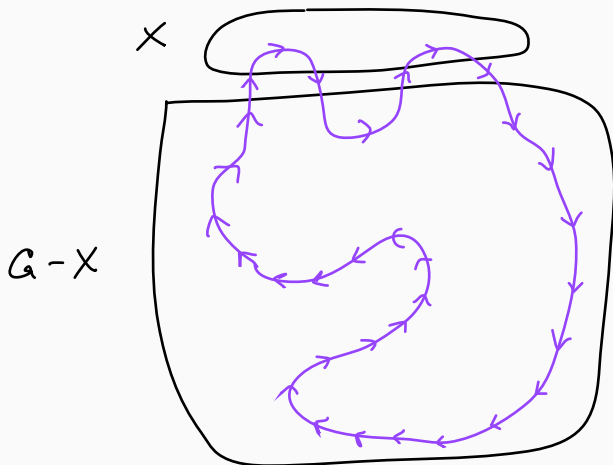
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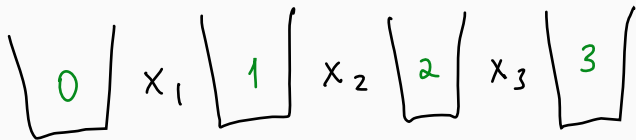
Algorithm for MinCSP($<$)

Iterative compression: $X \subseteq V$ s.t. $|X| \leq k + 1$ and $G - X$ is acyclic.



Algorithm for MinCSP($<$)

Let $\alpha : V \rightarrow \mathbb{Q}$ be opt. Guess $\alpha|_X$ in $2^{O(k)}$ time.

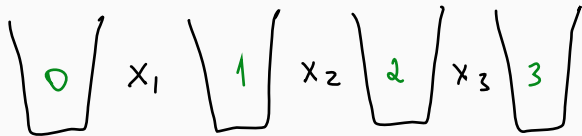


New goal: assign $V \setminus X$ into $|X| + 1$ buckets.

Introduce Boolean variables: $v \in V(G) \mapsto (v_0, \dots, v_{|X|})$.

Algorithm for MinCSP($<$)

Let $\alpha : V \rightarrow \mathbb{Q}$ be opt. Guess $\alpha|_X$ in $2^{O(k \log k)}$ time.



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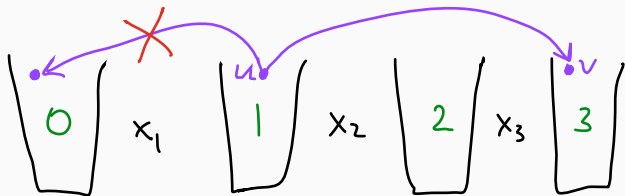
Introduce Boolean variables: $v \in V(G) \mapsto (v_0, \dots, v_{|X|})$.

Interpretation: $v_i = 1$ iff $\text{bucket}(v) \geq i$.

Ex: $\text{bucket}(v) = 3$, $v \mapsto (1, 1, 1, 1, 0, \dots, 0)$.

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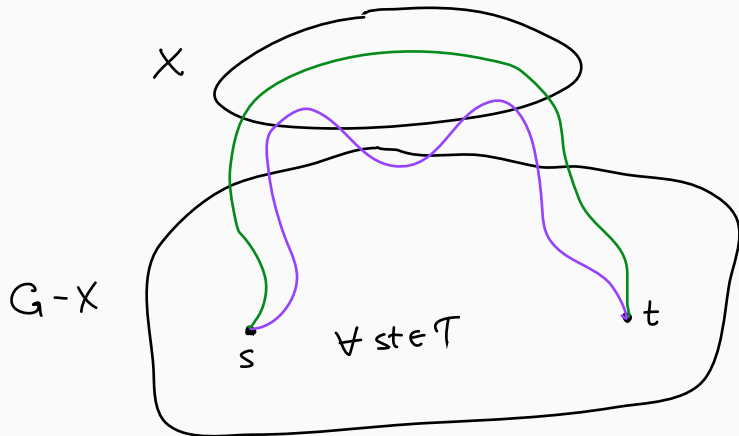
For every arc (u, v) in G , add constraint

$$\bigwedge_{i < j} (u_i \leftarrow u_j) \wedge \bigwedge_{i < j} (v_i \leftarrow v_j) \wedge \bigwedge_{i \leq j} (u_i \rightarrow v_j).$$

Algorithm for MinCSP(=, \neq)

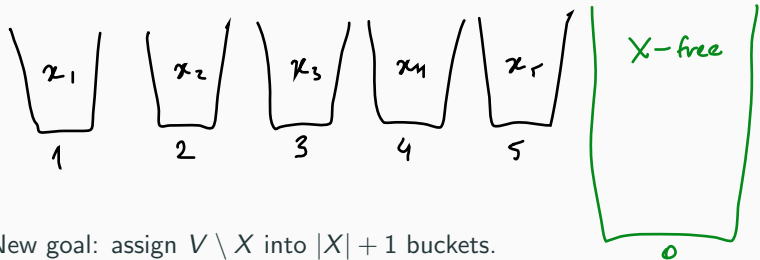
Input: graph G , set $\mathcal{T} \subseteq \binom{V}{2}$, integer k .

Compression: $X \subseteq V$ s.t. $|X| \in O(k)$ and X cuts all st -paths for $st \in \mathcal{T}$.



Algorithm for MinCSP(=, \neq)

Let $\alpha : V \rightarrow \mathbb{Q}$ be opt. Guess $\alpha|_X$ in $2^{O(k \log k)}$ time.



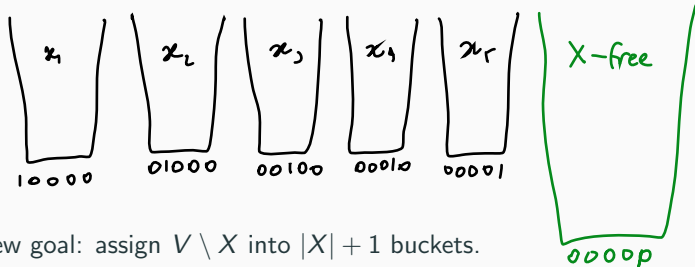
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Algorithm for MinCSP(=, \neq)

$k \log k$

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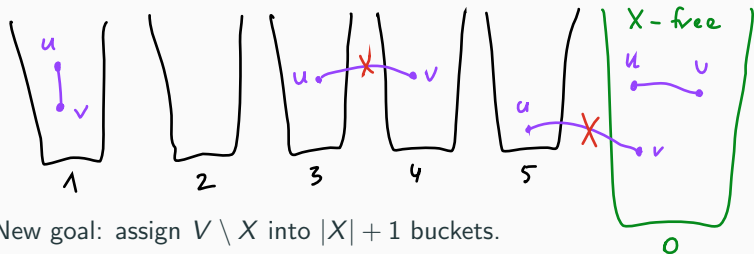
Introduce Boolean variables: $v \in V(G) \mapsto (v_1, \dots, v_{|X|})$.

If $\text{bucket}(v) = 0$, then $v \mapsto (0, 0, 0, \dots, 0)$.

If $\text{bucket}(v) = 2$, then $v \mapsto (0, 1, 0, \dots, 0)$.

Algorithm for MinCSP(=, \neq)

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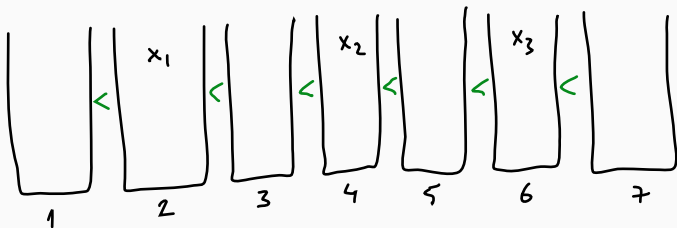
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For every edge uv in G , add constraint

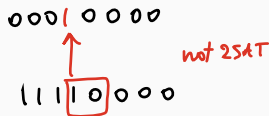
$$\underbrace{\bigwedge_{i < j} (\bar{u}_i \vee \bar{u}_j) \wedge \bigwedge_{i < j} (\bar{v}_i \vee \bar{v}_j)}_{\text{at most one 1}} \wedge \underbrace{\bigwedge_i (u_i \rightarrow v_i) \wedge \bigwedge_i (v_i \rightarrow u_i)}_{\vec{u} = \vec{v}}$$

Algorithm for MinCSP($<, =, \neq$)

Combine both encodings.



Crucial: $\text{component}(v) = i \implies \text{order}(v) = i$ can be enforced in $2K_2$ -free 2-SAT, not other way around:

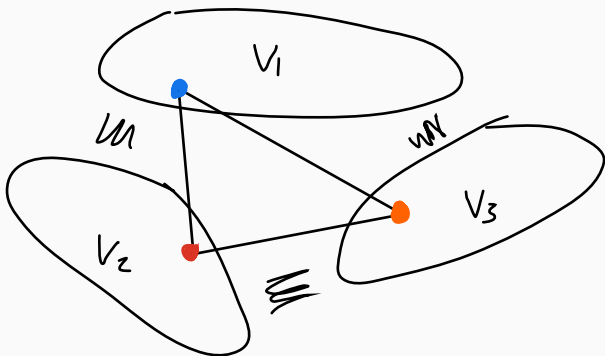


Lower Bound

W[1]-hardness of Directed Symmetric Multicut

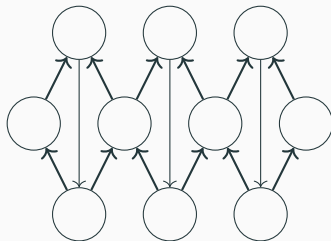
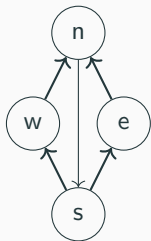
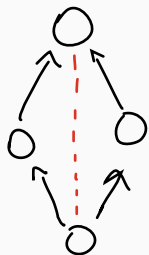
Directed Symmetric Multicut: given a digraph D , a set $\mathcal{T} \subseteq \binom{V}{2}$, and $k \in \mathbb{N}$, delete k arcs so that no pair in \mathcal{T} is strongly connected.

Reduction from Multicolored Clique: given G with $V(G) = V_1 \uplus \dots \uplus V_k$, find a clique with one vertex in each V_i .



W[1]-hardness of Directed Symmetric Multicut

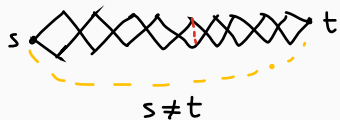
Diamond



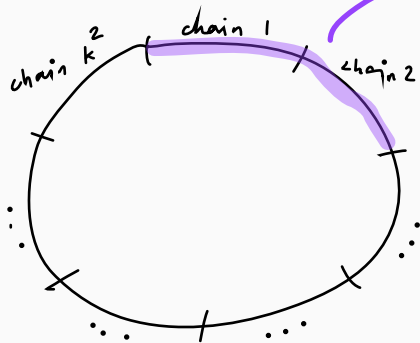
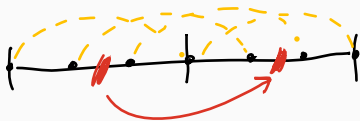
chain

W[1]-hardness of Directed Symmetric Multicut

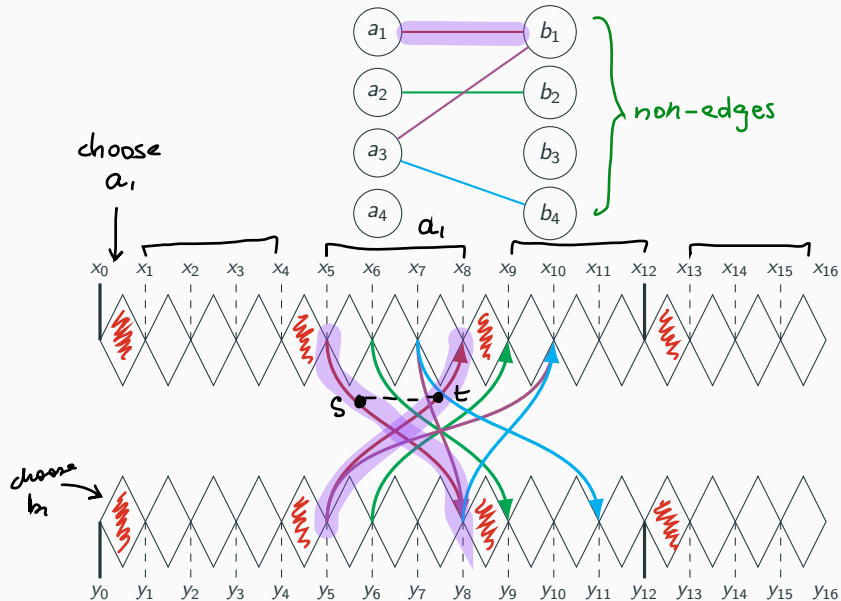
CHOICE



REPEAT



W[1]-hardness of Directed Symmetric Multicut



Conclusion

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Temporal relation is anything first-order definable using $<$

Ex.: $(x = y) \equiv \neg(x < y) \wedge \neg(x > y)$.

Ex.: $\text{Between}(x, y, z) \equiv (x < y \wedge y < z) \vee (z < y \wedge y < x)$.

Conclusion

We classify parameterized complexity of $\text{MINCSP}(\Gamma)$ for all $\Gamma \in \{<, >, \leq, \geq, =, \neq\}$.

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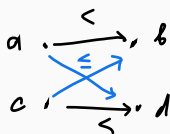
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Thank you!