

Solving Infinite-Domain CSPs Using the Patchwork Property

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- As a consequence, we obtain algorithms running in $f(w) \cdot O(n)$ time for CSPs over Allen's Interval Algebra, RCC8, etc.
- Connecting patchwork to *amalgamation*, we obtain results for temporal constraint satisfaction and phylogeny problems.

Constraint Languages

A constraint language consists of:

- a domain D ,
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The relations $\{R_1, R_2, \dots, R_m\}$ are:

- *jointly exhaustive* (JE) if $\bigcup_{i=1}^m R_i = D^k$,
- *pairwise disjoint* (PD) if $R_i \cap R_j = \emptyset$.

Constraint Satisfaction Problem (CSP)

CSP(\mathcal{B})

INSTANCE: (V, C) , V - variables, C - constraints of form $R(v_1, \dots, v_r)$, where R is a relation from \mathcal{B} and $v_1, \dots, v_r \in V$.

QUESTION: Is there an assignment f of values from to the domain of \mathcal{B} to the variables in V such that $(f(v_1), \dots, f(v_r)) \in R$ for all constraints in C ?

Example: CSP over Point Algebra

POINT ALGEBRA is binary constraint language with domain \mathbb{R} and relations $\{<, =, >\}$. We denote it by $(\mathbb{R}; <, =, >)$.

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Solution: $f(x) = 1, f(y) = f(w) = 2, f(z) = 3$.

Constructing Constraint Languages

Let \mathcal{B} be a k -ary constraint language with JEPD relations.

$\mathcal{B}^{\vee=}$ contains unions of all subsets of relations in \mathcal{B} .

Example: $(\mathbb{R}; <, =, >)^{\vee=}$ has relations $\{<, >, =, \leq, \neq, \geq, \top, \perp\}$.

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$\langle \mathcal{B} \rangle_{\text{b}}$ contains all relations definable using \mathcal{B} -formulas, i.e. logical formulas consisting of the relations in \mathcal{B} and symbols $(,), \wedge, \vee, \neg$.

Example: $\langle (\mathbb{R}; <, =, >) \rangle_{\text{b}}$ contains the relation R_{between} defined as $\{(x, y, z) \in \mathbb{R}^3 \mid (x < y \wedge y < z) \vee (x > y \wedge y > z)\}$.

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$$\mathcal{B} \subsetneq \mathcal{B}^{\vee=} \subsetneq \langle \mathcal{B} \rangle_{\text{b}}.$$

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If \mathcal{B} has an *infinite* domain, then we cannot enumerate all possible assignments in finite time.

However, if \mathcal{B} is k -ary and has JEPD relations, then we can enumerate all **complete certificates**, i.e. all satisfiable instances of $\text{CSP}(\mathcal{B})$ with constraints over all k -tuples of variables in V .

Certificates: Example

Let $\Gamma \subseteq \langle (\mathbb{R}; <, =, >) \rangle_b$ be a constraint language. An instance of $\text{CSP}(\Gamma)$ with 3 variables x, y, z has 13 complete certificates:

$$x = y, \quad x = z, \quad y = z$$

$$x = y, \quad x < z, \quad y < z$$

$$x = y, \quad x > z, \quad y > z$$

$$x < y, \quad x = z, \quad y > z$$

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Parameterized complexity studies the running time of algorithms with respect to a parameter $p \in \mathbb{N}$ and the input size n .

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A problem is in FPT if it admits an algorithm of form $f(p) \cdot n^{O(1)}$.

FPT \subsetneq XP.

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FPT \subsetneq XP.

We seek fpt algorithms for infinite-domain CSPs parameterized by the *primal treewidth*.

Primal Graph

A *primal graph* associated with an instance (V, C) of CSP has variables V as vertices and an edge for every pair u, v iff u and v appear in the scope of a constraint in C .

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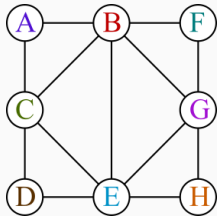
Example: Primal graph of the instance (V, C) of $\text{CSP}(\mathbb{R}; <, =, >)$, where $V = \{x, y, z, w\}$ and $C = \{x < y, y < z, x < z, y = w\}$, is



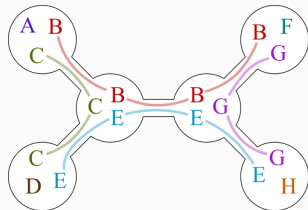
Treewidth

A tree decomposition of a graph G is a tree T and a mapping $X : T \rightarrow 2^V$ such that:

1. If $(u, v) \in E(G)$, then there is $t \in V(T)$ such that $u, v \in X(t)$.
2. For every $v \in V(G)$, the nodes t such that $v \in X(t)$ induce a non-empty connected subtree.



Graph G .



A tree decomposition of G .

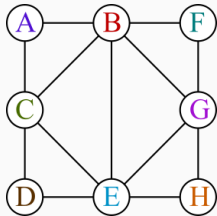
Treewidth

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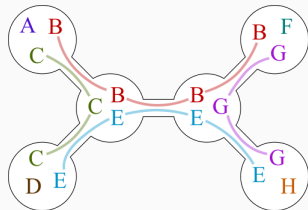
Width of (T, X) is the size of the largest $X(t)$ minus one.

Treewidth of G is the minimum width of a tree decomposition of G .

Primal treewidth is the treewidth of the primal graph.



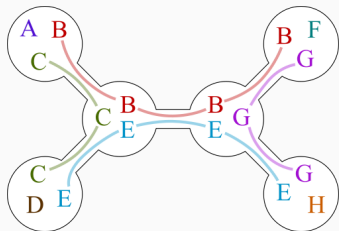
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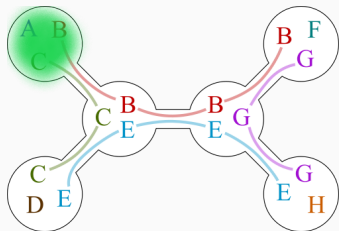
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Proposition: Finite-domain CSPs are solvable in $f(w) \cdot n^{O(1)}$ time.



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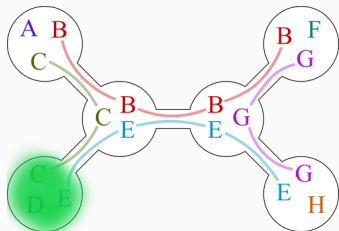
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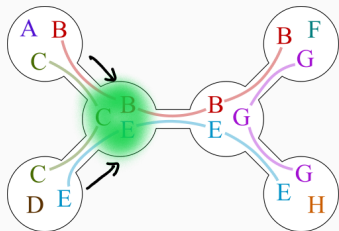
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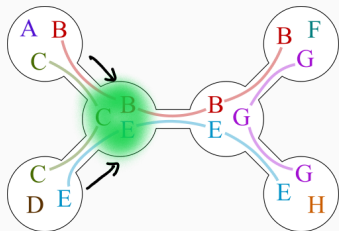
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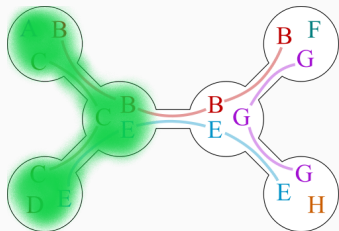
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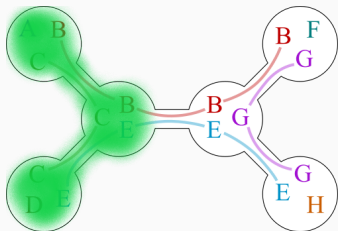
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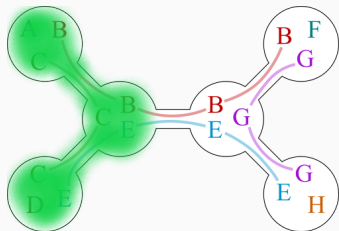
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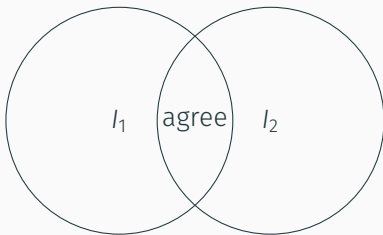
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A: Require the **patchwork property**.

Patchwork: Definition

Definition: A JEPD constraint language \mathcal{B} has *patchwork property* if for every pair of complete satisfiable instances $I_1 = (V_1, C_1)$ and $I_2 = (V_2, C_2)$ of $\text{CSP}(\mathcal{B})$ such that $I_1[V_1 \cap V_2] = I_2[V_1 \cap V_2]$, the instance $(V_1 \cup V_2, C_1 \cup C_2)$ is also satisfiable.



Theorem: Let \mathcal{B} be a finite k -ary constraint language with JEPD relations and the patchwork property. Assume $\text{CSP}(\mathcal{B})$ is decidable. For any finite constraint language $\Gamma \subseteq \langle \mathcal{B} \rangle_{\text{b}}$, $\text{CSP}(\Gamma)$ is fpt.

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More specifically, an instance of $\text{CSP}(\Gamma)$ is solvable in

$$\tau_{\mathcal{B}}(w + 1)^2 \cdot w^k \cdot O(n)$$

time, where $\tau_{\mathcal{B}}$ is the time complexity of enumerating complete instances of $\text{CSP}(\mathcal{B})$.

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Consequences: Allen's Interval Algebra

Basic relation		Example	Endpoints
I precedes J	p	<i>iii</i>	$I^+ < J^-$
J preceded by I	p⁻¹	<i>jjj</i>	
I meets J	m	<i>iiii</i>	$I^+ = J^-$
J met-by I	m⁻¹	<i>jjjj</i>	
I overlaps J	o	<i>iiii</i>	$I^- < J^- < I^+$,
J overl.-by I	o⁻¹	<i>jjjj</i>	$I^+ < J^+$
I during J	d	<i>iii</i>	$I^- > J^-$,
J includes I	d⁻¹	<i>jjjjjjj</i>	$I^+ < J^+$
I starts J	s	<i>iii</i>	$I^- = J^-$,
J started by I	s⁻¹	<i>jjjjjjj</i>	$I^+ < J^+$
I finishes J	f	<i>iii</i>	$I^+ = J^+$,
J finished by I	f⁻¹	<i>jjjjjjj</i>	$I^- > J^-$
I equals J	e	<i>iiii</i> <i>jjjj</i>	$I^- = J^-$, $I^+ = J^+$

$AIA \subseteq \langle (\mathbb{R}; <) \rangle_{fo} \implies CSP(\langle AIA \rangle_b)$ is solvable in $2^{O(w \log w)} \cdot O(n)$.

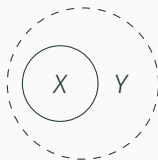
Consequences: RCC8



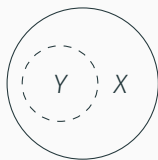
EQ(X, Y)



PO(X, Y)



NTPP(X, Y)



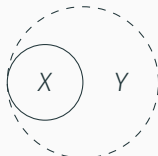
NTPP⁻¹(X, Y)



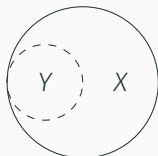
EC(X, Y)



DC(X, Y)



TPP(X, Y)



TPP⁻¹(X, Y)

RCC8 has patchwork \implies CSP(\langle RCC8 \rangle_b) is solvable in $2^{O(w^2)} \cdot O(n)$.

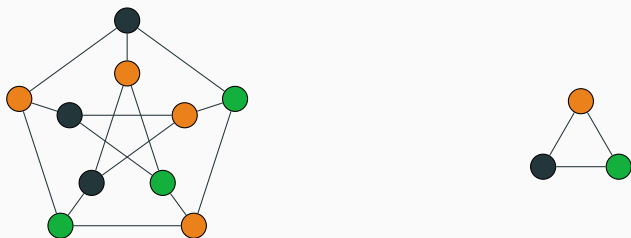
Model-Theoretic Point of View

CSP can be thought of a *homomorphism* problem between *relational structures*. A homomorphism is a mapping $h : \mathcal{A} \rightarrow \mathcal{B}$ that preserves relations, i.e. if $(a_1, \dots, a_r) \in R^{\mathcal{A}}$, then $(h(a_1), \dots, h(a_r)) \in R^{\mathcal{B}}$.

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For example, $\text{CSP}(\{0, 1, 2\}; \{\neq\})$ (aka GRAPH 3-COLORING) asks whether there is a homomorphism from an input graph G to K_3 .



Model-Theoretic Point of View

From the model-theoretic point of view, \mathcal{B} has patchwork if it has the *amalgamation property* (AP).

Theorem: If \mathcal{B} is *homogeneous*, then it has AP.

Homogeneity has been verified for many relational structures.

ω -categoricity is a more general property than homogeneity.

Bodisky & Dalmau have shown that $\text{CSP}(\Gamma)$ is in XP if $\Gamma \subseteq \langle \mathcal{B} \rangle_{\mathfrak{b}}$ and \mathcal{B} is ω -categorical, i.e. solvable in $n^{f(w)}$ time for some computable f .

Question: Is there an ω -categorical relational structure \mathcal{B} such that $\text{CSP}(\mathcal{B})$ is in XP but not in FPT (under plausible complexity-theoretic assumptions)?

Thank you!